



NOTE: (*) These dimension can be increased for low polarity motors, and must be confirmed together with detailed datasheet definition.
 (**) Dimensions dependent on the motor winding configuration.
 General tolerance: geometrical tolerance (ISO 2768-2) class K linear tolerance (ISO 2768-2) class M.
 (***) Suggested position for hydraulic connectors.
 (****) To calculate the minimum number of screws, use follows formulas:
 X (N° Stator screw)= Stack length * 0.115
 Y (N° Rotor screws)= Stack length * 0.144
 Calculation for screws property class 8.8
 The number of screws can be reduced using higher property classes.

Type: Squid Torque Motor
TK1150-xxx-yyy

